

# External control electronics for the SYDFE1 control of A10VSO axial piston pumps

## Analogue amplifier, configurable

**RE 30241/01.10**  
 Replaces: 08.06

1/8

**Type VT 5041**

From Component series 25



H6853\_d

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#### Card holder:

- Type VT 3002-2X/32, see RE 29928  
 Single card holder without power supply unit

#### Power supply unit:

- Type VT-NE32-1X, see RE 29929  
 Compact power supply unit 115/230 VAC → 24 VDC
  - Output 1 (60 W) for supplying amplifier card type VT 5041
  - Output 2 (25 W) for supplying pressure transducers; e.g. types HM 12 or HM 13, see RE 29933

### Features

- Integral part of the SYDFE1 pressure and flow control system (Component series 1X, 2X and 3X) for controlling A10VSO... axial piston unit with SYDFE1 control
- Implementation of the electronic functions of the SYDFE1 control; pressure and swivel angle control; optional power limiter
- Circuitry of the pressure controller can be matched to existing hydraulic fluid volumes (actuator plus lines)
- Differential amplifier inputs
- Controller for valve spool position
- Minimum value generator for pressure and swivel angle controller
- Self-locking output stage
- Pressure-related leakage compensation (can be switched of)
- Polarity reversal protection for power supply
- Switchable actual pressure value input (current, voltage, range)
- LED lamps on the front panel:
  - Error / no enable „H1“
  - Internal supply voltage „H2“
- Indicator instrument for actual swivel angle value on the front panel (optional)
- Power limiter with internal or external command value feed-forward (optional)

## Ordering code

VT 5041 -2X / / \*

External control electronics for the SYDFE1 control of A10VSO axial piston pumps

Component series 25 to 29  
(25 to 29: unchanged technical data and pin assignment)

= 2X

**Additional functions:**

- Without power limiter, without indicator instrument = 1
- With power limiter, with indicator instrument = 3

Further details in clear text

### Preferred types

Material no.	Type
R900749982	VT5041-2X/1
R900749983	VT5041-2X/3

## Functional description

VT 5041-2X analogue amplifiers are designed as plug-in cards in Euro-format. As a standard, they are provided with one command value input each for pressure and swivel angle [1] (power limiter, optional). The actual pressure value is sensed by a pressure transducer. A position transducer on the pump acquires the actual swivel angle value. The acquired actual values are processed in an amplifier [10 and 12] and compared with the injected command values. Minimum value generator [4] ensures that only the controller assigned to the relevant working point is automatically activated. The output signal of minimum value generator [4] becomes the command value for the closed control loop of the valve.

The optional power limiter is automatically activated by the feed-forward of a suitable command value. The power command value can be provided internally or externally. If required, it acts directly on swivel angle controller [3] via a minimum value generator [13].

The actual valve value (position of the valve spool) is acquired by an inductive position transducer. Oscillator/demodulator circuit [10] processes the signal. Valve spool position controller [5] determines and processes the system deviation. The output signal of valve controller [5] forms the command value for self-clocking current output stage [6], which controls the proportional solenoid of the valve.

The amplifier card has a failure notification output at which there is a voltage of 0 V in case of failure. Simultaneously, the „H1“ LED lights up and the output stage is de-energized.

The following events trigger an error message:

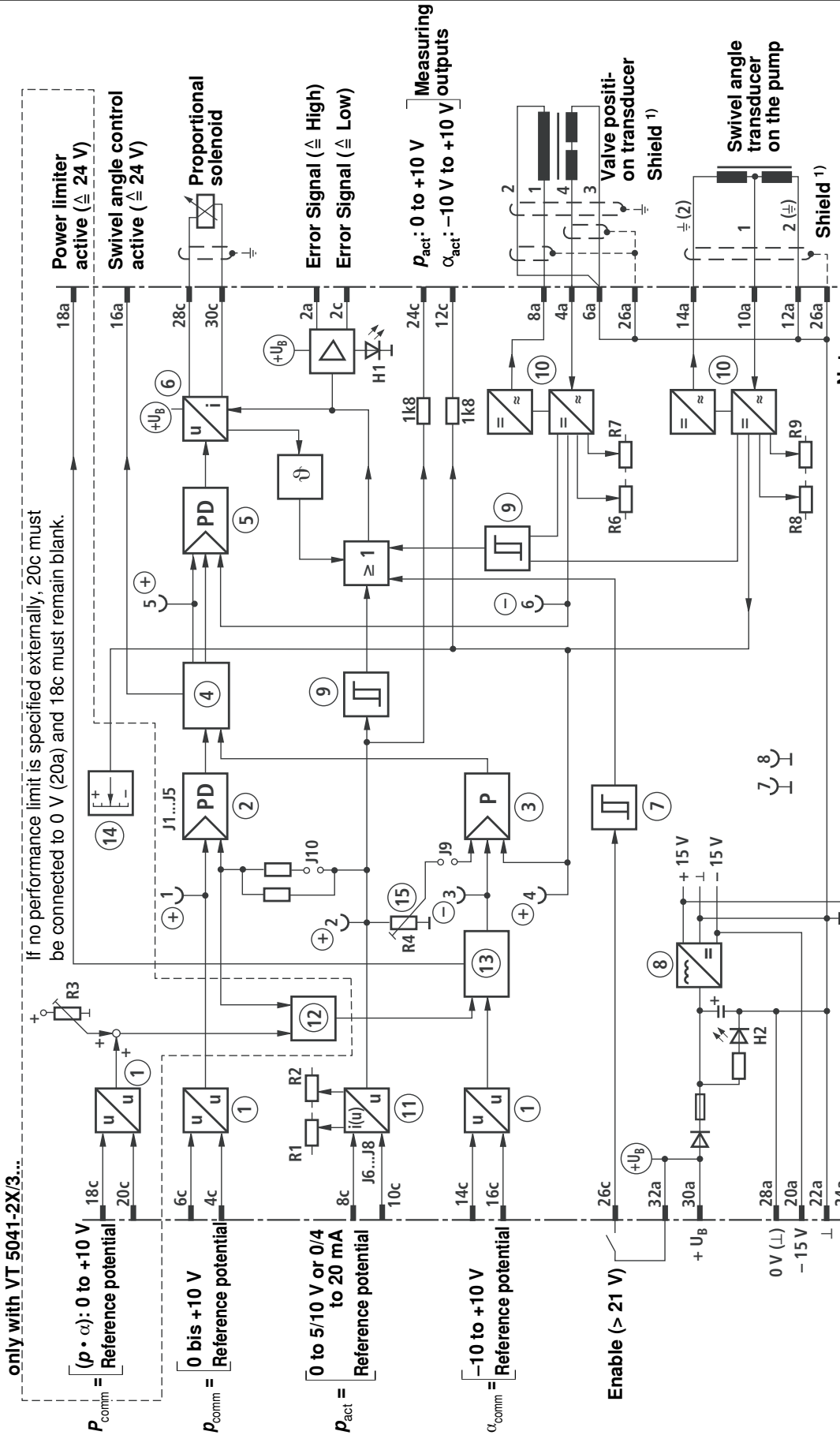
- Actual pressure value greater than permissible system pressure (socket 2  $p_{act} > 10 \text{ V}$ )
- Enable signal missing at connection 26c
- Excessive temperature of the output stage
- Cable break or range of swivel angle feedback exceeded
- Cable break or range of valve spool position feedback exceeded
- Cable break „proportional solenoid“
- Cable break „pressure transducer“ (only in conjunction with setting 4 to 20 mA)

In the case of an error, the output stage is deactivated and the valve spool pushed by a spring to its mechanical end position. The error can only be acknowledged by a reset of the enable signal.

The pressure-related pump leakage can be compensated for via the swivel angle control loop using potentiometer [15].

[ ] = Cross-reference to block circuit diagram on page 3

Block circuit diagram / pin assignment



only with VT 5041-2X/3...

If no performance limit is specified externally, 20c must be connected to 0 V (20a) and 18c must remain blank.

Power limiter active ( $\Delta \pm 24$  V)  
Swivel angle control active ( $\Delta \pm 24$  V)

Error Signal ( $\Delta$  High)  
Error Signal ( $\Delta$  Low)

Measuring outputs  
 $p_{act}$ : 0 to +10 V  
 $\alpha_{act}$ : -10 V to +10 V

Note:

- Connection of the swivel angle transducer is valid for clockwise rotating pump (") anti-clockwise rotating pump)
- Deviations between  $\alpha_{comm}$  (socket 3) and  $\alpha_{act}$  (socket 4) can also result from the setting of R4 (leakage compensation).

Explanation re indicator and adjustment elements (H, R), see page 6  
1) For notes on the shielding, see engineering notes for the complete system RE 30030-01-V

- 1 Differential amplifier
- 2 Pressure control
- 3 Swivel angle controller
- 4 Minimum value generator
- 5 Valve position controller
- 6 Output stage
- 7 Output stage enable
- 8 Power supply unit
- 9 Cable break detector
- 10 Oscillator/demodulator
- 11 Input amplifier
- 12 Divider
- 13 Min. value generator
- 14 Indicator instrument
- 15 Leakage compensation

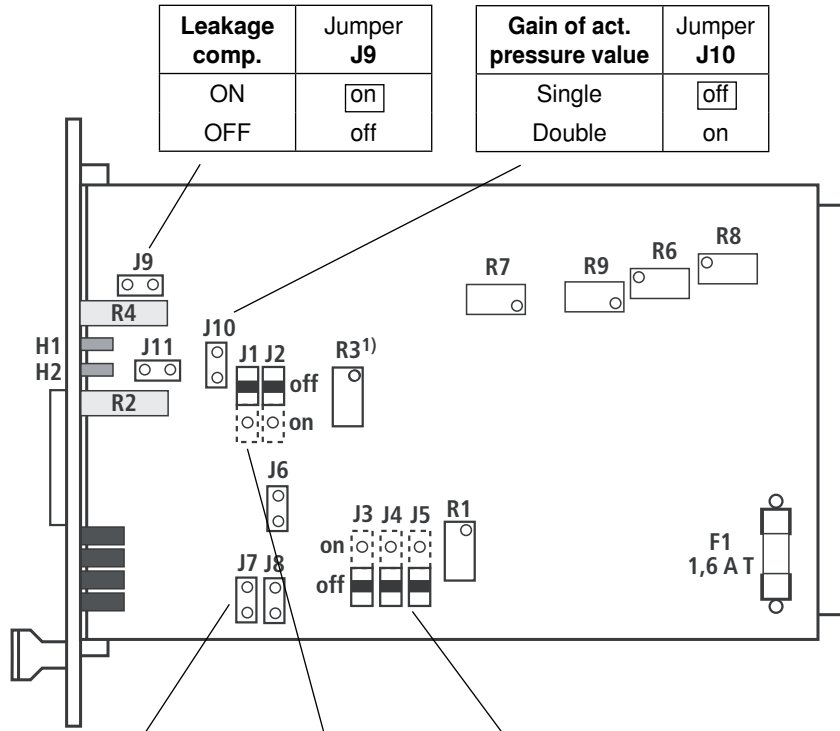
**Technical Data** (For applications outside these parameters, please consult us!)

Operating voltage	$U_B$	24 VDC +40 % -10 %
Operating range:		
– Upper limit value	$u_B(t)_{max}$	35 V
– Lower limit value	$u_B(t)_{min}$	21 V
Power consumption	$P_S$	35 VA
Current consumption	$I_{nom}$	0.6 A ( $I_{max} = 1.25$ A)
Fuse	$I_F$	1.6 A T
Inputs:		
– Command values (pressure, swivel angle)	$U_i$	0 to 10 V; $R_e = 100$ k $\Omega$
– Actual value (pressure)	$U_i$	0 to 5 V or 0 to 10 V; $R_e = 100$ k $\Omega$
	$I_e$	0 to 20 mA or 4 to 20 mA; $R_e = 500$ $\Omega$
– Power selection ( $p \cdot \alpha$ ) <sub>comm</sub> ( <b>only</b> with VT 5041-2X/3...)	$U_i$	0 to 10 V; $R_e > 100$ k $\Omega$
– Enable	$U_e$	> 21 V (use relay with contact for currents < 10 mA)
Outputs:		
– Output stage		
• Solenoid current / resistance	$I_{max}$	2.5 A; $R_{(20)} = 2$ $\Omega$
– Drivers for inductive transducers:		
• Oscillator frequency	$f$	ca. 5 kHz
• Voltage amplitude ( $U_{SS}$ )	$U_a$	10 V
– Signal voltage		
• Actual value (pressure, swivel angle)	$U$	0 to 10 V
• Swivel angle control active	$U$	$U_b - 1$ V
• Power limiter active ( <b>only</b> with VT 5041-2X/3...)	$U$	$U_b - 1$ V
– Auxiliary voltages	$U$	$\pm 15$ V $\pm 3$ %; 10 mA
– Error signal		
• L-active	$U_o$	$\geq U_B - 5$ V; 10 mA (short-circuit-proof); error at $U_o < 1$ V
• H-active	$U_o$	< 1 V; error at $\geq U_B - 5$ V; 10 mA
– Measuring sockets		
• Pressure command value ( $p_{comm}$ ) „1“	$U$	+10 V = 100 %
• Actual pressure value ( $p_{act}$ ) „2“	$U$	+10 V = 100 %
• Swivel angle command value ( $\alpha_{comm}$ ) „3“	$U$	-10 V = 100 %
• Actual Swivel angle value ( $\alpha_{act}$ ) „4“	$U$	+10 V = 100 %
• Spool position command value ( $s_{comm}$ ) „5“	$U$	$\pm 10$ V = $\pm 100$ %
• Actual spool position value ( $s_{act}$ ) „6“	$U$	$\pm 10$ V = $\pm 100$ %
Type of transducer:		
– for pump		IW 9 (throttle circuit; $\pm 4$ mm; 3-wire connection)
– for valve		DM2 (transformer circuit; $\pm 0.6$ mm; 4-wire connection)
Type of connection		32-pin male connector, DIN 41612, form D
Card dimensions		Euro-card 100 x 160 mm, DIN 41494

**Technical Data** (continuation)

Card dimensions:		
– Height		3 HE (128.4 mm)
– Width circuit board conductor side		1 TE
– Width component side		
• VT 5041-2X/1...		5 TE
• VT 5041-2X/3...		9 TE
Permissible operating temperature range	∅	0 to 50 °C
Storage temperature range	∅	-20 to +70 °C
Weight		
• VT 5041-2X/1...	m	0.19 kg
• VT 5041-2X/3...	m	0.21 kg

**Indicator / adjustment elements: VT 5041-2X/1 and VT 5041-2X/3 from Serie 25**



<b>Leakage comp.</b>	<b>Jumper J9</b>
ON	<input type="checkbox"/> on
OFF	<input type="checkbox"/> off

<b>Gain of act. pressure value</b>	<b>Jumper J10</b>
Single	<input type="checkbox"/> off
Double	<input type="checkbox"/> on

Actual pressure value for changover			
Input signal	Jumper position		
	J6	J7	J8
0 to 10 V	<input type="checkbox"/> off	<input type="checkbox"/> off	<input type="checkbox"/> off
0 to 5 V	<input type="checkbox"/> off	<input type="checkbox"/> off	<input type="checkbox"/> on
0 to 20 mA	<input type="checkbox"/> on	<input type="checkbox"/> off	<input type="checkbox"/> off
4 to 20 mA	<input type="checkbox"/> on	<input type="checkbox"/> on	<input type="checkbox"/> off

D-component of the pressure controller			
Hydraulic fluid volume (in litre) in the system (actuators plus lines)	Jumper position		
	J3	J4	J5
≤ 5,0	<input type="checkbox"/> off	<input type="checkbox"/> off	<input type="checkbox"/> off
7.5	<input type="checkbox"/> off	<input type="checkbox"/> on	<input type="checkbox"/> off
10.0	<input type="checkbox"/> on	<input type="checkbox"/> on	<input type="checkbox"/> off
15.0	<input type="checkbox"/> on	<input type="checkbox"/> off	<input type="checkbox"/> on
20.0	<input type="checkbox"/> off	<input type="checkbox"/> on	<input type="checkbox"/> on
25.0	<input type="checkbox"/> on	<input type="checkbox"/> on	<input type="checkbox"/> on

... Factory setting of jumpers

**Potentiometers:**

- R1** Zero point of actual pressure value
- R2** Actual pressure value adjustment  
factory setting:  
right-hand limit stop = max. gain
- R3<sup>1)</sup>** Power command value  
→ is added to an externally provided command value  
factory setting: left-hand limit stop = max. power
- R4** Leakage compensation  
(factory setting: left-hand limit stop = min. compensation)
- R6** Zero point of valve position transducer
- R7** Amplitude of valve position transducer (factory setting)
- R8** Zero point of swivel angle transducer
- R9** Amplitude of swivel angle transducer

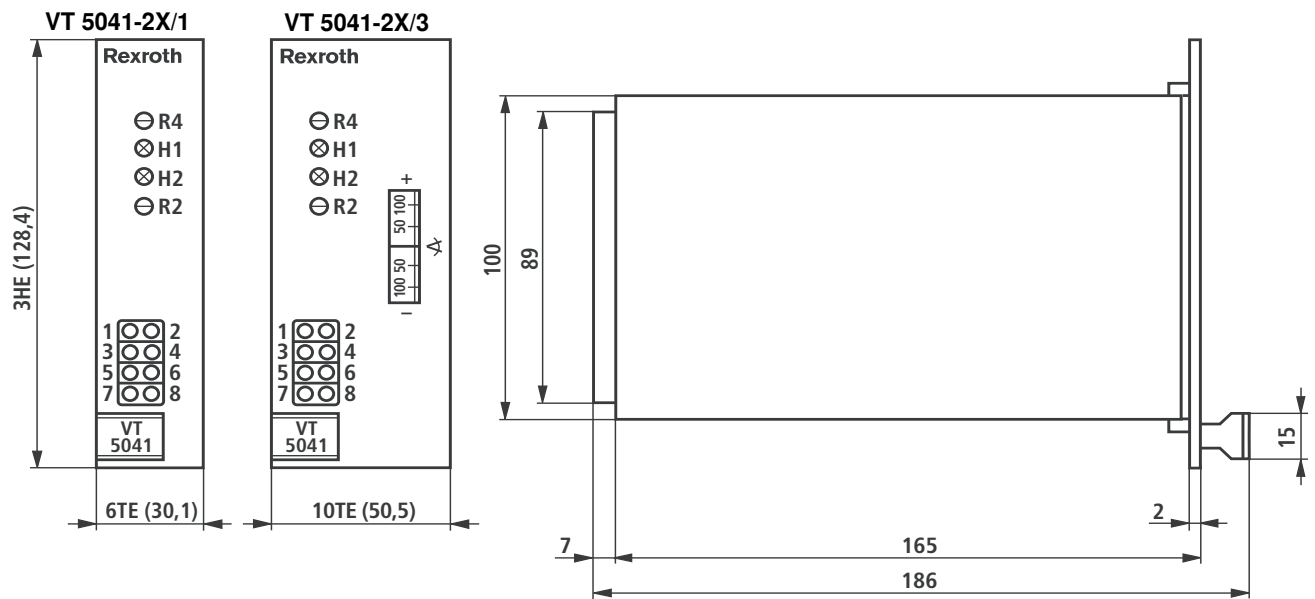
P-component of the pressure controller			
P-gain	Jumper position		
	J1	J2	J11
2	<input type="checkbox"/> on	<input type="checkbox"/> on	<input type="checkbox"/> on
2.4	<input type="checkbox"/> on	<input type="checkbox"/> off	<input type="checkbox"/> on
2.7	<input type="checkbox"/> on	<input type="checkbox"/> on	<input type="checkbox"/> off
3	<input type="checkbox"/> off	<input type="checkbox"/> on	<input type="checkbox"/> on
3.4	<input type="checkbox"/> on	<input type="checkbox"/> off	<input type="checkbox"/> off
4	<input type="checkbox"/> off	<input type="checkbox"/> off	<input type="checkbox"/> on
4.8	<input type="checkbox"/> off	<input type="checkbox"/> on	<input type="checkbox"/> off
8	<input type="checkbox"/> off	<input type="checkbox"/> off	<input type="checkbox"/> off

**LED lamps**

- H1** Error / no enable (red)
- H2** Internal voltage supply (green)

<sup>1)</sup> only with VT 5041-2X/3

## Unit dimensions (Dimensions in mm)



### Potentiometers:

„R2“ → Matching of amplitude  $p_{act}$  (pressure transducer)

„R4“ → Leakage compensation

### LED lamps:

„H1“ → Error / no enable

„H2“ → Internal supply voltage

### Measuring socket:

„1“ → Pressure command value  $p_{comm}$

„2“ → Actual pressure  $p_{act}$

„3“ → Swivel angle command value  $\alpha_{comm}$

„4“ → Swivel angle actual value  $\alpha_{act}$

„5“ → Spool position command value  $S_{comm}$

„6“ → Actual spool position value  $S_{act}$

„7“ and „8“ → Reference potential / ground

## Supplementary information

### Note:

Electrical signals processed by control electronics (e.g. actual value) must not be used for activating safety-relevant machine functions! (See also European standard "Safety requirements for fluid power systems and components – hydraulics", EN 982).

## Notes

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